

# Dependable Sensor Networks for Smart Cities

## – Research Position Statement –

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# Outline

- ▶ Group's General Research Interests
- ▶ Smart Cities and Sensor Networks
- ▶ Sensor Networks and Distributed Systems
- ▶ Dependable Sensor Networks
- ▶ Replication of Data and Services
- ▶ Self-Stabilization
- ▶ Region Adherence

# System Software and Distributed System Group

## General Research Interests

- ▶ Distributed Systems
- ▶ Distributed Algorithms
- ▶ Dependability, Fault Tolerance
- ▶ Replication, Self-Stabilization, Region Adherence
- ▶ Dependability Measures, Performance, Energy Efficiency
- ▶ Scalability, Dynamics, Graceful Degradation, Consistency Notions
- ▶ Sensors for Environmental Phenomena

# Smart Cities and Sensor Networks

## Smart Cities Characteristics

Smart Cities use **information technology** to

- 1) make efficient use of resources to support strong & healthy economic/social/cultural development,
- 2) to foster innovative processes, collective intelligence, and citizen participation,
- 3) learn, adapt, and innovate, and thus are able to respond more efficiently and promptly to changing circumstances by improving the intelligence of the city.

WHAT MAKES A CITY **SMART?**



(picture taken from [smartcities.ieee.org](http://smartcities.ieee.org))

# Smart Cities and Sensor Networks

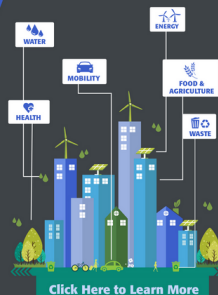
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→ information technology plays an **important role in the SC context**

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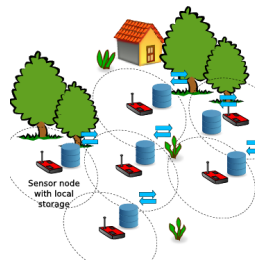
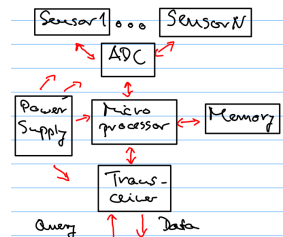


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## Sensor Network Characteristics

### Sensor Networks

- ▶ consist of relatively **cheap** Sensor Nodes (SNs) being often matchbox-sized computers
- ▶ SNs are **very resource-limited** in terms of computing power, memory, and energy if no external power supply is attached
- ▶ SNs have **mission-related sensors** (and actors) attached
- ▶ communicate often via **wireless communication** standards like ZigBee with each other
- ▶ can be **easily deployed**
- ▶ may communicate through **gateway** nodes to LANs and WANs

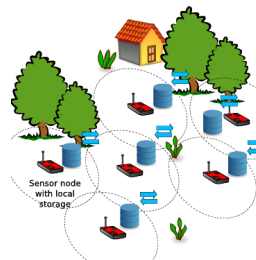
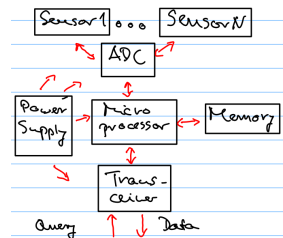


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→ in the following, Sensor Networks are referred to as **Wireless Sensor Networks** (WSNs)



# Smart Cities and Sensor Networks

## WSN as Part of Smart Cities' Information Technology

For example, in a Smart City, WSNs can be used to

1) monitor e.g.

- air quality
- fresh water and sewage quality
- fresh water consumption and sewage production
- river and sewage system levels etc.

through connected, integrated SNs,

2) allowing citizens e.g.

- inspect data collected by these SNs and
- to set up and add their own sensors and SNs to the network,

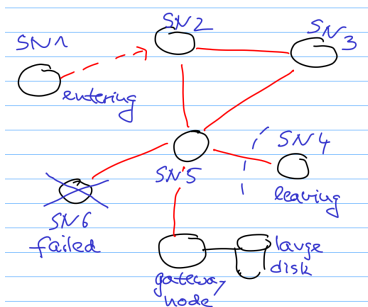
3) thereby enabling e.g.

- precise localization of and
- timely response to

critical situations.



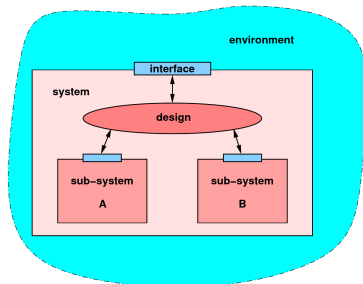
# Sensor Networks and Distributed Systems



- ▶ conceptually, WSNs are **distributed systems**
- ▶ in the SC context, often, they
  - are **dynamic**: SNs **enter or leave** the WSN over time
  - must **scale**: # of SNs of WSN may **strongly increase** over time
  - must be **dependable**: WSN must achieve its mission despite some **failed sub-systems**

# Dependable Sensor Networks

- ▶ **dependable distributed system** can be realized through **fault tolerance**
- ▶ **Fault Tolerance**
  - construction of highly dependable systems based on **failure-prone sub-systems**
  - **some sub-systems may fail** but system is **not rendered useless or incorrect**  
→ “tolerates failures to some extent”
- ▶ **Fault Tolerance Classes**
  - fail-stop fault tolerance
  - masking fault tolerance
  - non-masking fault tolerance
- ▶ **Fault Tolerance Concepts**
  - **replication**
  - **self-stabilization**
  - **region adherence**



	live	not live
safe	<b>Masking Fault-Tolerant</b>	<b>Fail-Stop Fault-Tolerant</b>
not safe	<b>Non-Masking Fault-Tolerant</b>	<b>Not Fault-Tolerant</b>

# Replication of Data and Services

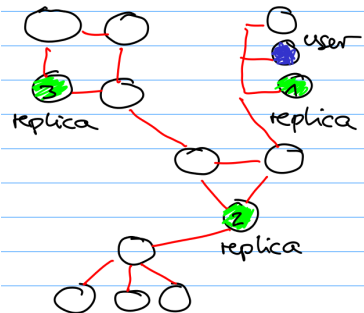
- ▶ create copies of data → **replicas**
- ▶ **access operations** are performed on a **subset** of replicas thereby **honoring** a given **consistency notion** → e.g. 1SR
- ▶ a **replication strategy (RS)** defines access operations, consistency notion, availabilities and costs

## General Aim

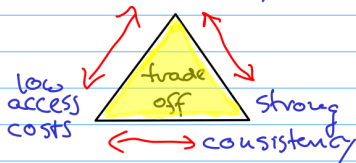
- ▶ guarantee **high availability** and **at the same time low costs** of data access operations

## Problems

- ▶ there is **no single best RS**
- ▶ **subtle relation** availability ↔ costs
- ▶ **fault model** and **workload** key to good solutions



high access  
availability



# Replication of Data and Services

## Aim in WSN context

- ▶ store and provide sensed data

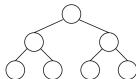
## Problems in WSN context

- ▶ access costs must be low since energy is restricted
- ▶ at the same time: data must be highly available since data might be crucial
- ▶ WSN: dynamic, large, subject to faults

## Our Contributions

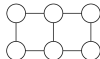
- ▶ easy replacement of obsolete replication strategies if WSN has changed substantially → replication framework
- ▶ synthesis of mission-optimized replication strategies  
→ by genetic algorithm (GA)

Logarithmic Protocol  
Tree Quorum Protocol



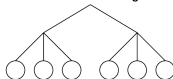
$$O(\log n)$$

Grid Protocol



$$O(\sqrt{n})$$

Hierarchical Quorum Consensus  
Multi-Level Voting

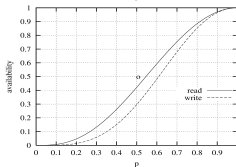
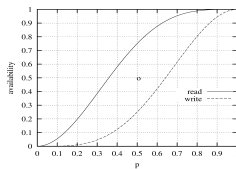


$$O(n^{0.63})$$

Triangular Grid

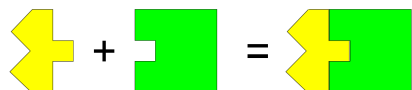
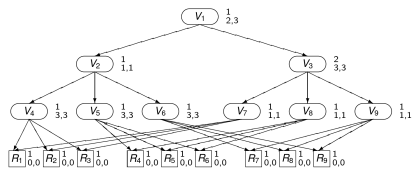
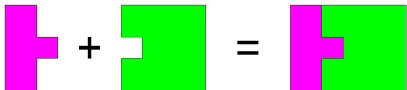
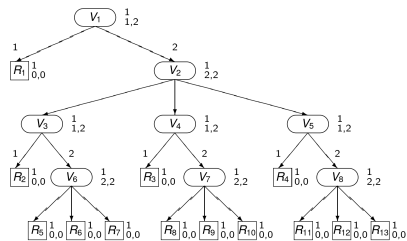


$$O(\sqrt{n})$$



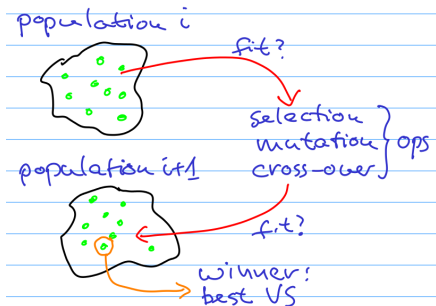
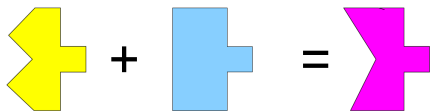
## Replication Framework Approach

- ▶ replication strategy is modeled as a **voting structure** (VS)
- ▶ **general mechanism** interprets VS **at run-time** leading to the RS's behavior in terms of access availabilities and costs
- ▶ RS A can be replaced by RS B simply by changing the VS
- ▶ **no coding**, only reconfiguration, possible even at run-time



## Genetic Algorithm Approach

- ▶ specify desired properties of RS via constraint system  
→ fitness function, fitness value
  - ▶ known replication strategies are represented as VSs
  - ▶ VSs are the individuals of a GA population
- 1) select initial population
  - 2) apply genetic operators (selection, mutation, cross-overs) and fitness check in order to create new generation
  - 3) repeat Step 2) for some time or until desired fitness is met
  - 4) use VS (= RS) with highest fitness obtained



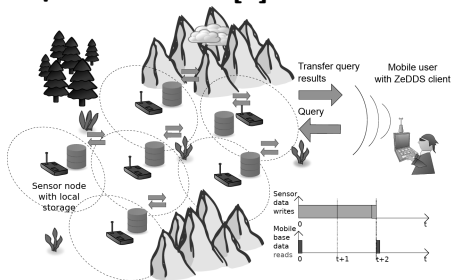
## Example of a Sensor Network with Replicated Data [1]

### ► WSN setting

- sensors collect data
- **data sink** is mobile and often **beyond communication range**
- **measured data** should **not get lost** in the meantime , e.g., due to failed SNs
- data is **stored within** the **WSN** itself
- **energy** within WSN is **limited**

### ► ZeDDS approach

- stands for “dependable and energy-efficient data management in WSNs”
- **data is replicated according to some RSs** → trade-off availability vs. energy costs



### ► ZeDDS approach (Cont.)

- RSs are represented by **VS**
- RSs can be changed at **run-time**
- sink can **harvest data** from any SN **when in communication range**
- **harvested data** can subsequently **be deleted**

# Self-Stabilization

A system  $A$  is **self-stabilizing** wrt. a set of states  $P$  if

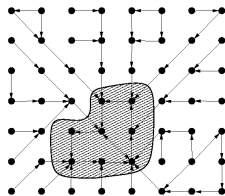
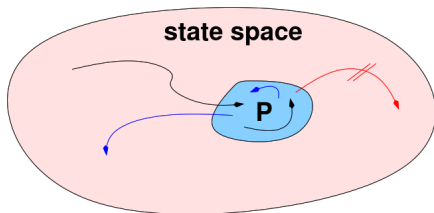
- ▶ (**Convergence**): regardless of its initial state,  $A$  reaches a state in  $P$  in finite steps and
- ▶ (**Closure**): once in state in  $P$ ,  $A$  does not subsequently leave  $P$ .

## General Aim

- ▶ guarantee **autonomous, uninitialized functioning** of a distributed system despite any **transient faults**

## General Problems

- ▶ self-stabilizing systems (SSS) are **complicated to design**
- ▶ SSS properties are likely to be **destroyed under composition**
- ▶ SSS are **complicated to formally prove correct**





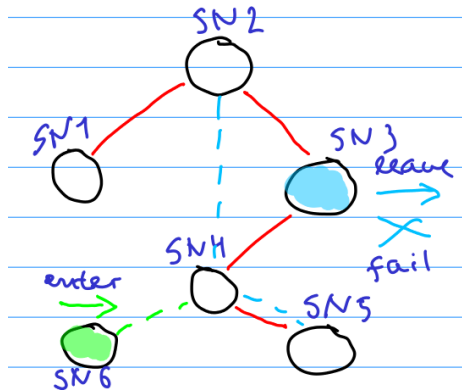
# Self-Stabilization

## Aim in WSN context

- ▶ provide high **availability** of a **WSN's communication backbone** when SNs **fail** or **leave** or **enter** the system

## Problems

- ▶ SSS are normally only **analyzed** in terms of convergence after the last fault  
→ **convergence yes?/no?**
- ▶ but here, due to **network dynamics**, SSS must be analyzed under **ongoing fault assumptions**
- ▶ which **SS spanning tree algorithm** provides **high connectivity** under these assumptions?

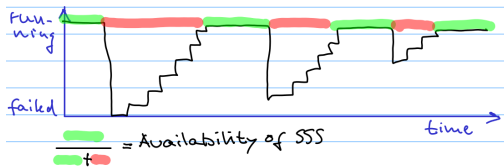
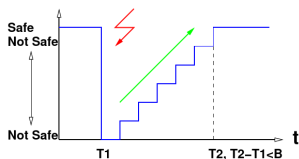


## Our Contributions

- ▶ **notion of availability** of SSS
- ▶ **availability optimization** of a SSS

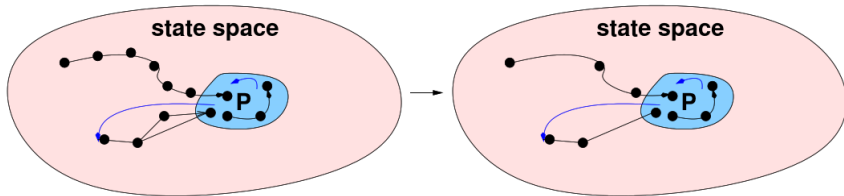
## Availability of SSS

- ▶ when in  $P$ , a SSS does **useful work** → system is **available**
- ▶ when not in  $P$ , some **illegal behavior** may be observed → system has **failed**
- ▶ (limiting) **availability** of a SSS is the **probability that SSS is in  $P$**  at an arbitrary point in time
- ▶ when **two SSSs** solve the same problem, then the system with the **higher availability** might be the **better choice**



## Availability Optimization Approach

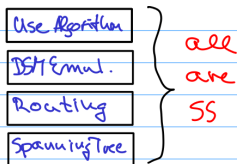
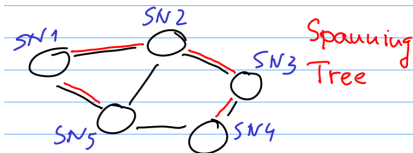
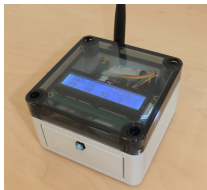
- ▶ analyze SSS using **probabilistic model checking**
- ▶ **analyze** resulting “**fault tree**”
- ▶ modify SSS: **shorten** existing paths
- ▶ modify SSS: **introduce short-cut** paths
- ▶ modify SSS: **eliminate too long** paths



- ▶ **less** “time spent outside P” → **availability** is **increased**

## Example of a Self-Stabilizing Sensor Network [2]

- ▶ SNs equipped with
  - brightness sensor
  - push button
  - LC Display
- ▶ each SN
  - **measures** brightness when button pressed
  - **calculates average brightness** of all current brightness values of SNs and
  - displays it
- ▶ SNs may **fail**, **join**, or **leave** the system autonomously
- ▶ WSN **self-stabilizes** to states where **all SNs display the average brightness**



## Region Adherence

A **region-adherent system (RAS)**

- ▶ **gracefully degrades** the service quality provided by the system **per fault up to some maximal number of faults** and
- ▶ degradation is **upper-bounded per fault**

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### Formal Definition

We assume a system with configurations  $C$ , initial configurations  $C_0$  and algorithm  $\mathcal{A}$  under fault model  $\mathcal{F}$ . Let  $g : C \mapsto [0, 1]$  be a function stating the service quality of the system and let  $f$  be a natural number.

$r : \{0, \dots, f\} \mapsto [0, 1)$  is a non-decreasing function with  $r(0) = 0$  and  $r(f) < 1$ . Algorithm  $\mathcal{A}$  is called  *$f$ -region-adherent wrt.  $g$ ,  $r$ , and  $\mathcal{F}$* , if and only if for all reachable configurations  $c \in C$ , all initial configurations  $c_0 \in C_0$ , and all executions  $\gamma = c_0 \cdots c$  ending in  $c$  the following holds:

$$g(c) \geq 1 - r(\#\mathcal{F}\backslash\mathcal{A}(\gamma)), \quad (1)$$

where  $\#\mathcal{F}\backslash\mathcal{A}(\gamma)$  represents the number of fault steps of execution  $\gamma$ . A system executing an  $f$ -region-adherent algorithm is also called  $f$ -region-adherent.

# Region Adherence

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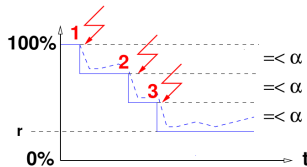
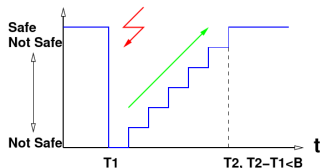
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## General Aim

- ▶ **guarantee a priori-known minimal service quality** even after some number  $f$  of faults
- ▶  $f$ -region-adherent

## General Problems

- ▶ region adherent systems are **complicated to design**
- ▶ RAS properties are likely to be **destroyed under composition**
- ▶ RAS are **complicated to formally prove correct**



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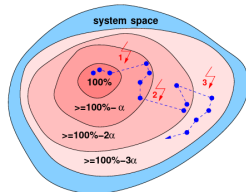
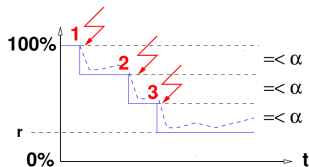
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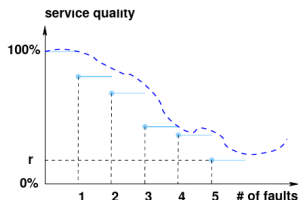
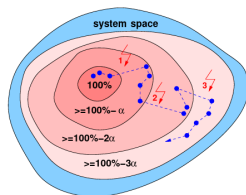
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# Region Adherence

## Aim in WSN context

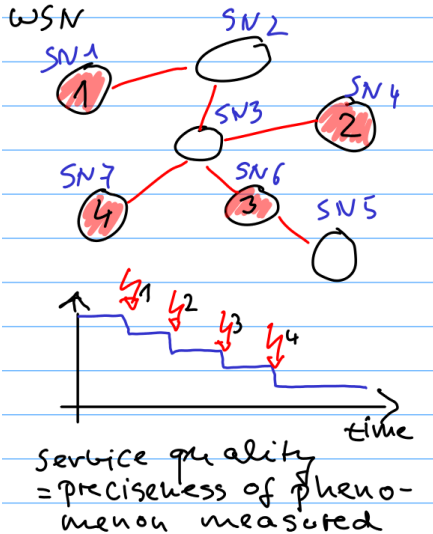
- ▶ sense distributed phenomenon with gracefully degrading quality if some sensors fail

## Problems

- ▶ how to find RAS that provably reduce service quality very slowly?
- ▶ how to find RAs that withstand a large number of faults prior to delivering 0 service quality?

## Our Contributions

- ▶ notion of maximizing extension of a RAS
- ▶ hardening transformation of RAS

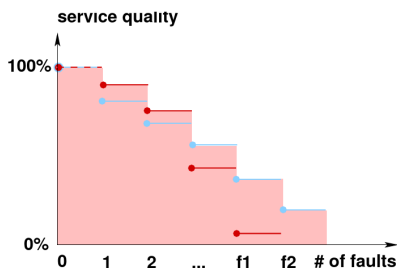


## Maximizing Extension Approach

- ▶ given two RAS  $A$  and  $B$  using the same algorithm  $S$  and offering the same notion of service quality  $g$
- ▶ RAS  $A$  is known to be a  $f_1$ -region-adherent with quality reduction function  $r = \langle r_0, r_1, \dots, r_{f_1} \rangle$
- ▶ RAS  $B$  is known to be a  $f_2$ -region-adherent with quality reduction function  $r' = \langle r'_0, r'_1, \dots, r'_{f_2} \rangle$
- ▶ and w.l.o.g.  $f_1 \leq f_2$ .
- ▶ Then, we know that there is a RAS  $C$  using algorithm  $S$  offering service quality notion  $g$  that is  $f_2$ -region-adherent with quality reduction function  $r'' = \langle \min(r_0, r'_0), \dots, \min(r_{f_1}, r'_{f_2}), r'_{f_1+1}, \dots, r'_{f_2} \rangle$
- ▶ Thus, there exists a RAS  $C$  (and we know it) that potentially withstands more faults and/or reduces service quality not that much per fault

## Maximizing Extension Approach (Cont.)

- ▶ RAS  $A$  has been proven to
  - have quality reduction function given in **red**
  - be  $f_1 = 4$ -region-adherent
- ▶ RAS  $B$  has been proven to
  - have quality reduction function given in **blue**
  - be  $f_2 = 5$ -region-adherent
- ▶ RAS  $C$  is guaranteed to
  - be  $f_2 = 5$ -region-adherent
  - having the “**red area**” quality reduction function
- ▶ a RAS implementing algorithm  $S$  is **actually better** in terms of region-adherence **then** it was **previously known**
- ▶ due to its RA properties, algorithm  $S$  **may now be eligible for actual use** in a WSN context

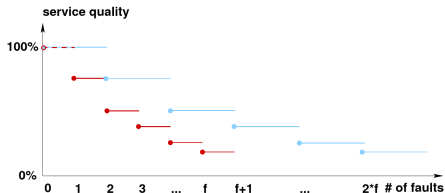


## Hardening Transformation Approach

- ▶ Idea: transform  $f$ -region-adherent system into  $(n + 1)f$ -region-adherent system by hardening the system against faults
- ▶ up to now: system switched to new region after single new fault
- ▶ from now on: system
  - remains for 1 to  $n$  faults in current region
  - switches to new region after  $n + 1$ st new fault
- ▶ new system is obviously much more RA

### Transformation

- ▶ all variables are replicated  $2n + 1$  times



### Transformation (Cont.)

- ▶ reading a variable: replaced by a function that delivers the majority value of the  $2n + 1$  replicas<sup>a</sup>
- ▶ writing a variable: replaced by a function that writes the new value to all  $2n + 1$  replicas

<sup>a</sup> and writes this value back to all  $2n + 1$  replicas

## Example of a Region-Adherent Sensor Network [3]

- ▶ WSN measures **air humidity in a region**
- ▶ SNs equipped with humidity sensors each
- ▶ SNs **send measured value** to a data sink (**gateway node**)
- ▶ SN may fail; in any case, they send a (potentially incorrect) humidity value

$$v_i \in \begin{cases} [l, u] & \text{if failed} \\ [v - \epsilon, v + \epsilon] \cap [l, u] & \text{else} \end{cases}$$

$v$  is the true air humidity value physically present

- ▶ **gateway node calculates a mean value**

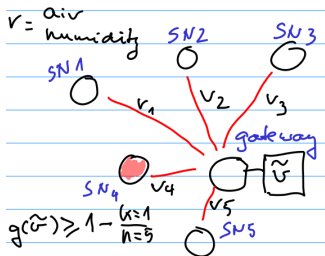
$$\tilde{v} := \frac{1}{n} \sum_{i=0}^{n-1} v_i$$

- ▶ with service quality function

$$g(\tilde{v}) := \min \left\{ 1 - \frac{|\tilde{v} - v| - \epsilon}{u - l}, 1 \right\},$$

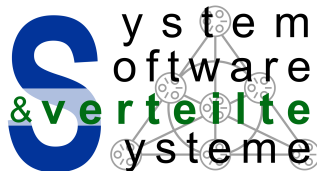
it holds that  $g(\tilde{v}) \geq 1 - k/n$  with  $0 \leq k < n$  being the # of faults occurred

- ▶ WSN is  **$(n - 1)$ -region-adherent**



# Conclusion

- ▶ WSNs for SCs must be
  - scalable
  - fault-tolerant
  - able to cope with dynamics
- ▶ realizable through FT concepts
  - replication
  - self-stabilization
  - region adherence
  - and combinations thereof
- ▶ gave examples of WSNs using these concepts



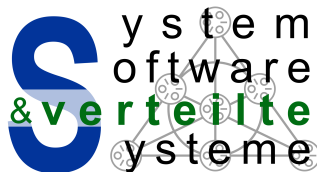
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# Conclusion

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  - and combinations thereof
- ▶ gave examples of WSNs using these concepts
- ▶ looking forward to cooperations with you on these topics



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Thank you for attending 😊



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