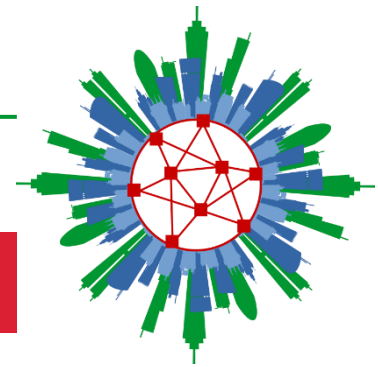




SuMoCoS

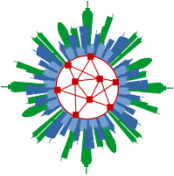
Sustainability and Mobility
in the Context of Smart Cities



Smart mobility solutions

Dr. Fatih Özel

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Key business segments of OECON



We are one of the world's leading providers of cutting-edge testing and location-based smart mobility solutions for manufacturers in the automotive industry and associated industries.

eCall & TPSP



eCall test systems for the automotive industry and eCall decoders for emergency response centers and TPSP

Connected & automated driving



Test- and Simulation systems for V2X cars
Location-based smart mobility solutions

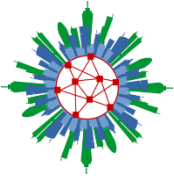
UAV Management



DaaS - "Drone as a Service"
Management software Platform for Drone flights beyond Line of sight (BVLOS)

OECON is the world market leader in this environment

TPSP: Third party service provider
V2X: Vehicle-to-everything



1. Ecall test systems

- Test and development server
- Simulator
- Router



2. UAV management

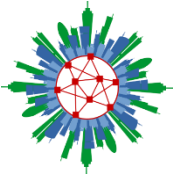
- OECON Hawk core platform
- OECON Hawk product family
- Hawk core platform features



3. Location-based smart mobility solutions

- Examples of our projects



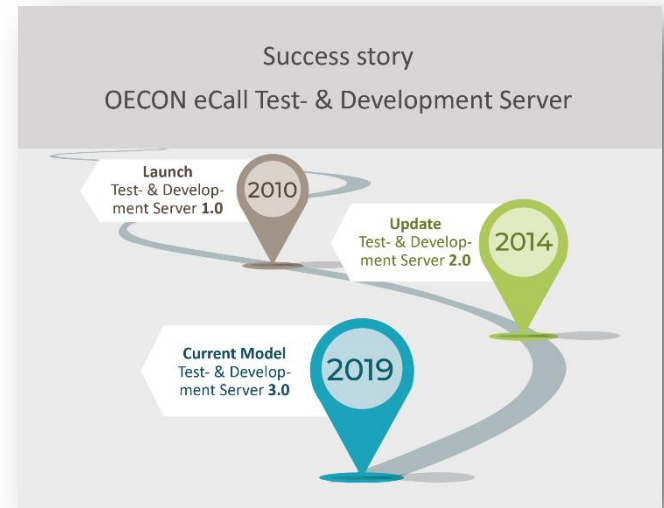


1. Ecall test systems



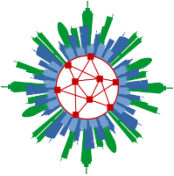
OECON is global market leader in eCall test systems and key partner for EU-funded eCall projects since 2010 (i.e. HeERO, HeERO2, I_HeERO and sAFE Projects)

- Our products **support**:
 - eCall and location data development
 - upgrading 112 centers and third party service (TPS) providers with eCall and location data
- Our eCall **product range**:
 - Test and development server
 - Simulator
 - Router



Some of our customers





1. Ecall test systems



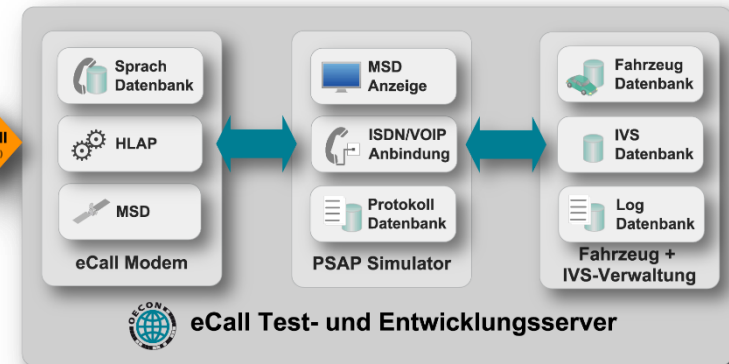
eCall test and development server

Certified service centre for receiving eCalls in compliance with EU and ERA-GLONASS specifications.

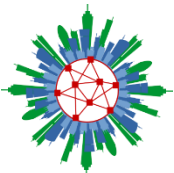
- Reference Test platform for **OEMs and suppliers**
- Supports **In-Vehicle System (IVS)** developers for eCall component development
- Complete, easy-to-use application for **PSAP simulation**
- Supports up to **100 simultaneous calls**
- Supports **next generation eCall (eCallNG)**
- Detailed process logs with reproducible test results



112 eCall
(MSD+Sprache)



PSAP: Public safety answering point



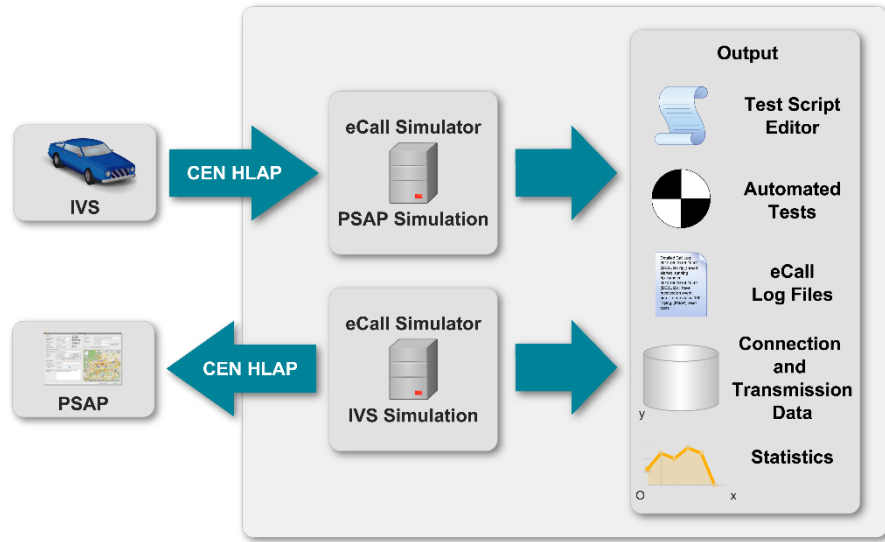
1. Ecall test systems

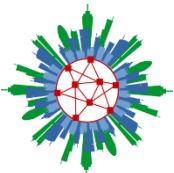


eCall simulator

Platform for validation and certification of IVS and 112 center components

- **Certified** system (TÜV Süd Germany) with **compliance** to all relevant **eCall standards**
- **Automated testing** with TTWorkbench and TTCN/3 test script language
- Test and data **reports** with **statistics**





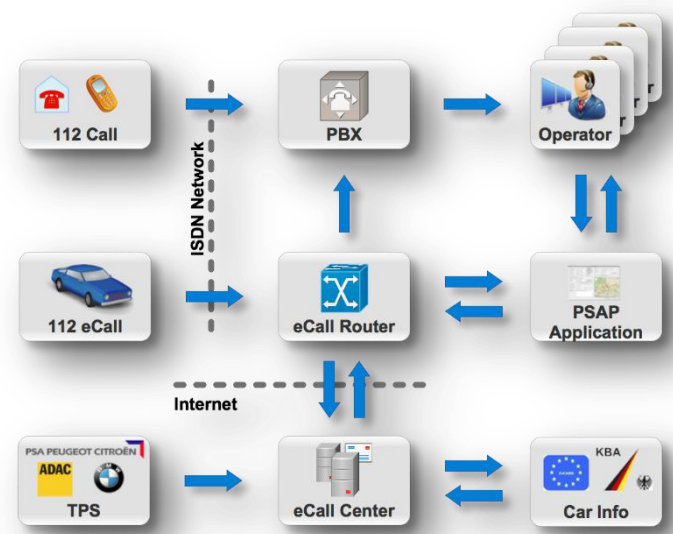
1. Ecall test systems



eCall router

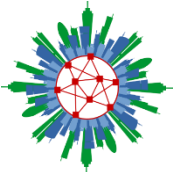
Platform for **upgrading PSAPs** with minimum effort and investment

- An add-on to existing PBX and PSAP applications
- Uses unified XML interfaces to communicate with the PSAP software and standard ISDN features to communicate with the PBX
- **Certified** system by TÜV Süd Germany
- Up to 100 simultaneous calls
- Used for **over 300.000 eCalls** since 2011
- Supports both pan-European and TPS eCalls
- Used by several **TPS providers** since 2014



Third Party Services

ISDN: Integrated services digital network
 PBX: Private branch exchange



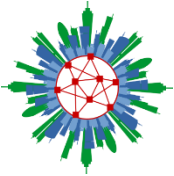
1. Ecall test systems



PSAPs with our eCall router

- Fire brigade and police departments in Denmark
- eCall Pilot Filtering Instance PSAP in Belgium
- **PSAPs in:**
 - Portugal
 - Bulgaria
 - Netherlands
 - Latvia
 - Iceland
 - Central eCall PSAP in France
 - Finland
 - Cyprus
 - Germany



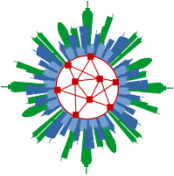


1. Ecall test systems



Our worldwide eCall business





2. UAV management

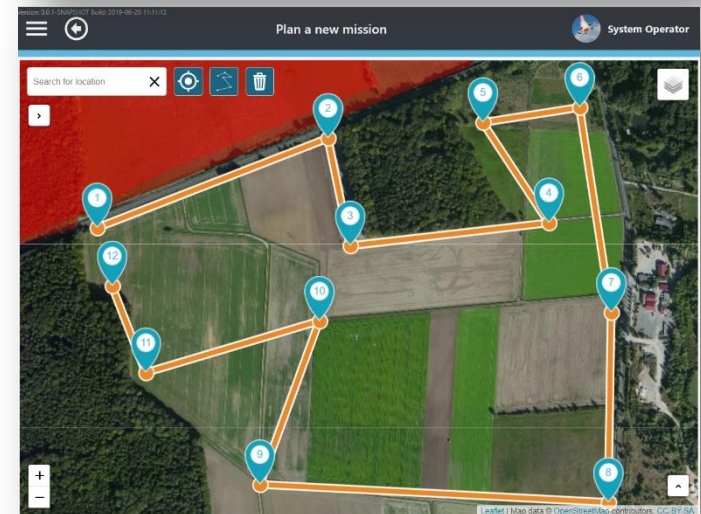


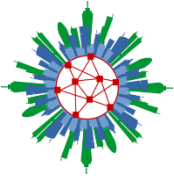
OECON Hawk Core Platform

Integrate aerial data into your day-to-day operations and improve business workflows.

- **Plan** sophisticated commercial drone operations
- **Manage** missions, users, drones and airspace conditions
- **Configure** and **customize** your settings
- **Strategize** and tactically collaborate

We offer **tailor-made solutions** for a variety of tasks.



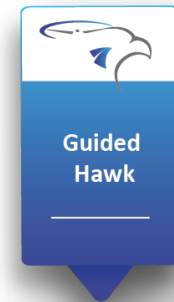


2. UAV management



OECON Hawk Product Family

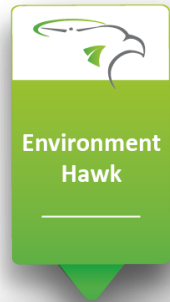
- **Guided Hawk:**
Site monitoring with scheduled, recurring surveillance missions and delivery of video streams and high-resolution images
- **Emergency Hawk:**
Ad-hoc drone missions for rescue services and police forces with the ability to share the video stream with those involved and to control the drone on-site
- **Environment Hawk:**
Advanced missions for environmental protection, i.e. taking water samples for quality determination or dropping tree seeds for reforestation.



Guided
Hawk



Emergency
Hawk



Environment
Hawk

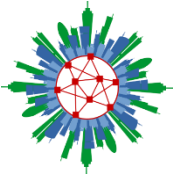
Functional Services

Technical Support Services

Business Support Services



Hawk Core Platform



2. UAV management



Hawk Core Platform: Plan sophisticated drone operations

Plan missions instantly by drawing on a map

Adjust mission parameters easily based on specific requirements

Plan a new mission

System Operator

Search for location

Waypoints: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12

Leaflet | Map data © OpenStreetMap contributors, CC-BY-SA

Plan a new mission

System Operator

Name

Start: 28.06.2019 10:10

Drone: No drone selected

Action upon completion: Return to home

Save mission

Save template

Load template

Flight information

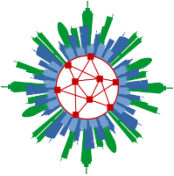
- Total distance: 5.44 km
- Estimated duration: 18m 7s

Weather information

- Temperature forecast: 11.8 °C (Min: 11.6, Max: 20.7)
- Wind speed forecast: 1.5 m/s
- Wind direction: 289.0 °
- Pressure: 1026.4 hPa
- Total precipitation: 0.0
- Precipitation duration: 0.0

Waypoint information

Address	Height (m)	Speed (m/s)	Turn mode
Höseweg, 38104 Braunschweig, Germany	20	5	Stop and turn
K 141, 38104 Braunschweig, Germany	20	5	Stop and turn
K 141, 38104 Braunschweig, Germany	20	5	Stop and turn
K 141, 38162 Cremlingen, Germany	20	5	Stop and turn
K 141, 38162 Cremlingen, Germany	20	5	Stop and turn
K 141, 38162 Cremlingen, Germany	20	5	Stop and turn



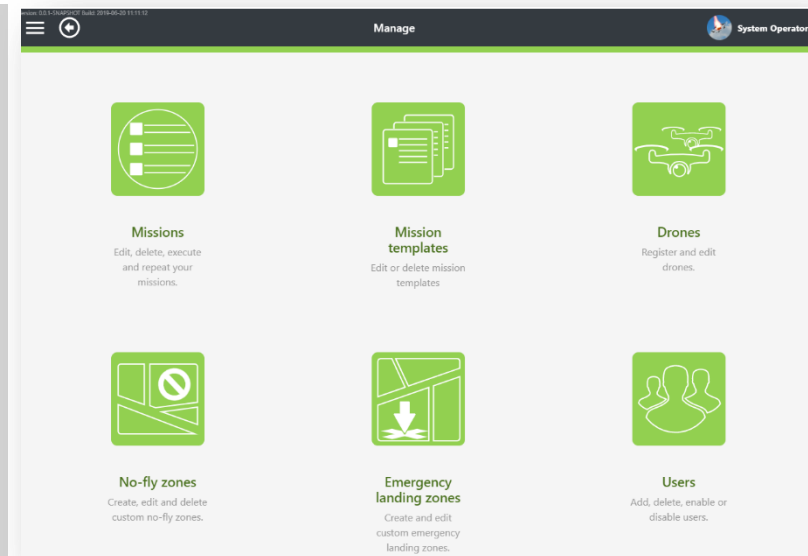
2. UAV management

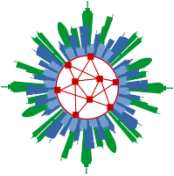


Hawk Core Platform: Manage your team, equipment and processes

Missions, flight crews, equipment, and operational procedures are in one integrated place

- **Manage** past and upcoming missions with required details
- **Command** unmanned aircraft for their assigned tasks remotely
- **Simulate** your missions before actual operations
- **Monitor** flight parameters, and **analyze** the summary of missions with required details
- **View** and edit your mission templates
- **Create** no-fly zones and emergency landing zones for safer operations
- **Assign** defined roles to users across your organization
- **Register, identify** and **manage** your drones easily





2. UAV management



Hawk Core Platform: Configure and customize your settings

Select your personal and mission related settings for desired usability

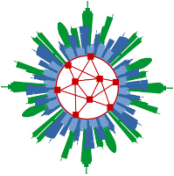
Customize your user profile:

- **Edit** your profile information password & preferences
- **Track** your past actions

Configure your flight settings:

- **Edit** and **set** specific flight parameter

The screenshot displays two screens from the Hawk Core Platform. The top screen is the 'My profile' page, which includes a navigation menu, a user profile icon, and four main settings cards: 'Profile information' (with a sub-description 'Profile information.'), 'Action log' (with a sub-description 'Track your past actions.'), 'Change password' (with a sub-description 'Edit your password.'), and 'Personalisation' (with a sub-description 'Edit your preferences.'). The bottom screen is the 'Flight settings' page, featuring a 'save' button, a drone icon, and several adjustable parameters: 'Waypoint radius (m)' with a dropdown menu, 'Low battery level trigger (%)' with a dropdown menu, 'Critical battery level trigger (%)' with a dropdown menu, 'Hovering time after GPS loss (s)' with a dropdown menu, 'Maximum inclination' with a slider, 'Maximum vertical speed' with a slider, and 'Maximum rotation speed' with a slider. The bottom right corner of the flight settings screen shows the 'OECON AIR MOBILITY SERVICES' logo.



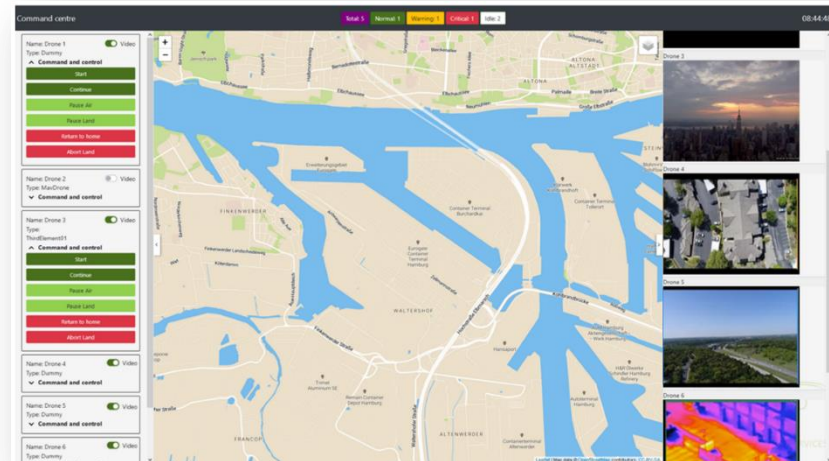
2. UAV management

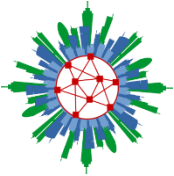


Hawk Core Platform: Coordinate your missions with command centre

Deploy, strategize and tactically cooperate by receiving real-time views of a scene with minimal latency

- **Monitor** the status and the real time location of the drones in-field
- **Generate** instant aerial insights in seconds with live video streaming
- **Take manual control** over camera
- **Mark points** of interest on the map to indicate locations for detailed inspection
- **Secure** telemetry and network connectivity
- **Store** flight logs, video and data usage





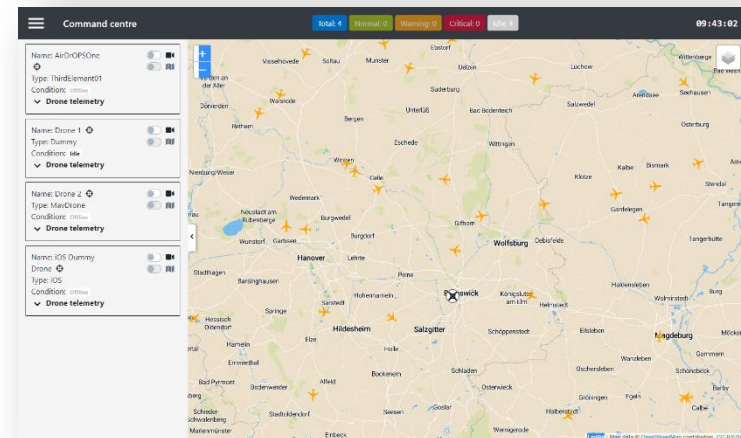
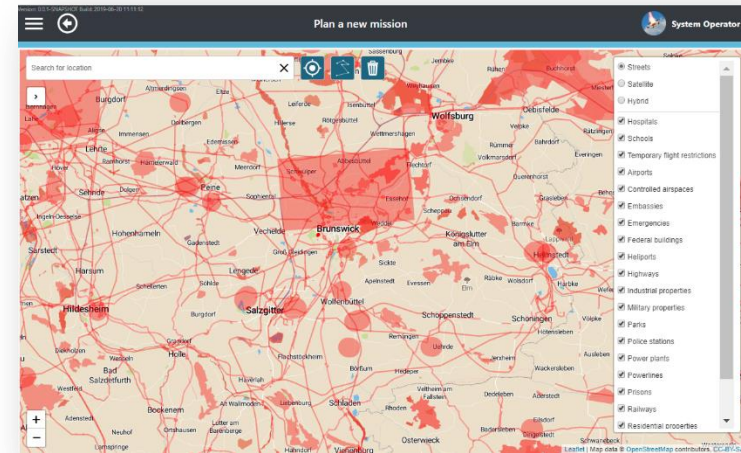
2. UAV management

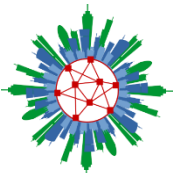


Hawk Core Platform

Compliance with static and dynamic no-fly zones: Required documents are submitted to the related aviation authority.

- **Pilot in Command:** Only licensed pilots are authorized to operate the drones
- **Compliance with standards:** The platform is developed with compliance to emerging standards
- **Configuration options:**
 - **Control software:** Customer provides his/her own drones. Drones can be integrated easily to the software thanks to its open interfaces
 - **Complete package:** Includes control software and required drone as well as software and hardware maintenance contracts.
- **Integration** into existing IT environments and **video conferencing systems**





3. Location-based smart mobility solutions

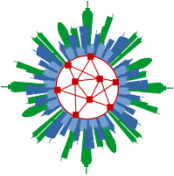


We are reliable partner in numerous projects with its cutting-edge location-based products and services, especially in the transportation domain

Example domains of location based services



Figure reference: https://www.researchgate.net/publication/327256471_Location_based_services_ongoing_evolution_and_research_agenda

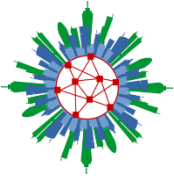


3. Location-based smart mobility solutions



Examples of our projects

Projects	Start Date	Area	Description
<i>RFID Airport Baggage Handling</i>	2005	Logistics	System study to optimize the process chain of baggage handling by using RFID technology
<i>Ring&Ride</i>	2005	Personal Mobility	Multifunctional mobile phone ticketing system
<i>SOPHA</i>	2005	Personal Mobility	Integration of a GNSS software receiver for safety-critical PDA applications
<i>TrafficOnline</i>	2005	Automotive	Online traffic data collection via mobile communications networks
<i>BSSdW 2007</i>	2006	Personal Mobility	GPS positioning of relay runners and transfer of the location data to digital map of Old Town Square in Braunschweig
<i>FAMOS Phase I</i>	2006	Automotive	Satellite navigation with GPS / EGNOS and Galileo for safety-critical driver assistance systems and location-based mobility services
<i>SARHA</i>	2006	Personal Mobility	Sensor-augmented EGNOS/Galileo receiver for handheld applications in urban and indoor environments
<i>WLAN Ortungspark</i>	2006	Other projects	WLAN positioning in indoor and outdoor areas
<i>ZasterLaster</i>	2006	Other projects	Mobile cash dispenser supported by innovative location technology
<i>Brainworxx Halbmarathon 2007</i>	2007	Personal Mobility	GPS tracking of runners and transfer of location data to digital map; GPS transmitters were mounted on bicycles

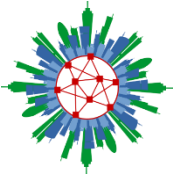


3. Location-based smart mobility solutions



Examples of our projects

Projects	Start Date	Area	Description
<i>Braunschweiger Nachtlauf 2007</i>	2007	Personal Mobility	GPS tracking of runners and transfer of location data to digital map; GPS transmitters were mounted on bicycles
<i>FAMOS Phase II</i>	2007	Automotive	Satellite navigation with GPS / EGNOS and Galileo for safety-critical driver assistance systems and location-based mobility services
<i>GNSS-INDOOR</i>	2007	Personal Mobility	GNSS innovative technologies and their demonstration for indoor positioning
<i>GoPORT</i>	2007	Logistics	Galileo based location method to improve processes at airports
<i>Braunschweiger Nachtlauf 2008</i>	2008	Personal Mobility	GPS tracking of runners and transfer of location data to digital map; GPS transmitters were mounted on bicycles
<i>Mobile real time traffic service</i>	2008	Automotive	Real-Time Traffic Data Service - A method for the comprehensive determination of traffic disruptions based on anonymised mobile network data
<i>GALAPAGOS</i>	2009	Logistics	Galileo-based seamless and robust positioning applications for logistics optimization processes
<i>Gamma-A</i>	2009	Automotive	Galileo mass market satellite navigation receiver for cars
<i>GENEVA</i>	2009	Automotive	Galileo / EGNOS Enhanced driver assistance system
<i>IEGLO</i>	2009	Personal Mobility	Infrastructure-Augmented EGNOS/Galileo Receiver for Personal Mobility (IEGLO)

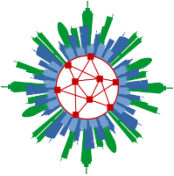


3. Location-based smart mobility solutions



Examples of our projects

Projects	Start Date	Area	Description
Logiloc	2009	Logistics	Product development for container management
Sichere Schiene	2009	Logistics	Secure rail traffic through intelligently interconnected location-based telematics systems
Simba	2012	Personal Mobility	"Safe and mobile by means of accompanying assistance systems"
IKTS	2013	e-Mobility	Project 3.2 in the electric mobility showcase of Lower Saxony - "Mapping and Positioning Service"
InMoBS	2013	Personal Mobility	Urban mobility support for the blind and visually impaired at signalised junctions
ANIKA	2014	Automotive	Upgrade of emergency call pillars on motorways with V2I (Vehicle to Infrastructure) communication
Parkplatzortung via RFID	2015	Automotive	RFID based smart parking system
C-Roads	2017	Automotive	Development of uniform standards & communication solutions for C-ITS applications in Europe
Digitaler Knoten	2017	Automotive	Development of digital solutions for supporting vulnerable road users in the context of connected and automated driving in intra urban areas
Testfeld Niedersachsen	2017	Automotive	Connected and automated driving testbed in Lower Saxony



Contact us for more information and possible collaborations!



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